

DESIGN MODELS

Design models accommodate qualitative, categorical variables.

Consider a model for three means, \bar{y}_1 , \bar{y}_2 , and \bar{y}_3 .

$$\begin{aligned}\bar{y}_1 &= \mu + \alpha_1 + e_1 \\ \bar{y}_2 &= \mu + \alpha_2 + e_2 \\ \bar{y}_3 &= \mu + \alpha_3 + e_3 \quad \rightarrow \quad \bar{y}_i = \mu + \alpha_i + e_i\end{aligned}$$

$$\bar{y}_i = \mu + \alpha_1 x_{i1} + \alpha_2 x_{i2} + \alpha_3 x_{i3} + e_i$$

$$\begin{aligned}\bar{y}_1 &= 1 & 1 & 0 & 0 \\ \bar{y}_2 &= 1 & 0 & 1 & 0 \\ \bar{y}_3 &= 1 & 0 & 0 & 1\end{aligned}$$

$$\begin{bmatrix} \bar{y}_1 \\ \bar{y}_2 \\ \bar{y}_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} + \begin{bmatrix} e_1 \\ e_2 \\ e_3 \end{bmatrix}$$

$$\underline{\bar{y}} = \mathbf{X} \underline{\alpha} + \underline{e} \quad \text{where } \mathbf{X} \text{ is the design matrix}$$

In this case, $\hat{\underline{\alpha}} \neq (\mathbf{X}'\mathbf{X})^{-1} \mathbf{X}'\underline{y}$ since $|\mathbf{X}'\mathbf{X}| = 0$

In all design models, $|\mathbf{X}'\mathbf{X}| = 0$; design models are of deficient rank.

In our case, column 1 = column 2 + column 3 + column 4.

Example/

		α : Type of Twins	
		Monozygotic	Dizygotic
β : Gender	Male	\bar{y}_{11}	\bar{y}_{12}
	Female	\bar{y}_{21}	\bar{y}_{22}

We have an additive main class model; containing only main effects.

$$\begin{bmatrix} \bar{y}_{11} \\ \bar{y}_{12} \\ \bar{y}_{21} \\ \bar{y}_{22} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \underline{e}$$

$$\underline{\bar{y}} = \mathbf{A} \underline{\xi} + \underline{e}$$

Since \mathbf{A} is of deficient rank, we cannot invert the matrix to solve the equations.

We can “reparameterize” the model to solve the deficiency problem.

$$\text{Add equations: } \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} = \mathbf{D} \rightarrow \begin{cases} 0 = \alpha_1 + \alpha_2 \\ 0 = \beta_1 + \beta_2 \end{cases}$$

Which suggests that $\sum \alpha_i = 0$ & $\sum \beta_i = 0$; ANOVA assumptions

This results in:

$$\begin{bmatrix} \underline{y} \\ \dots \\ \underline{0} \end{bmatrix} = \begin{bmatrix} \mathbf{A} \\ \dots \\ \mathbf{D} \end{bmatrix} \underline{\xi} + \begin{bmatrix} \underline{e} \\ \dots \\ \underline{0} \end{bmatrix}$$

$$\underline{\xi} = \left(\begin{bmatrix} \mathbf{A} \\ \dots \\ \mathbf{D} \end{bmatrix}' \begin{bmatrix} \mathbf{A} \\ \dots \\ \mathbf{D} \end{bmatrix} \right)^{-1} \begin{bmatrix} \mathbf{A} \\ \dots \\ \mathbf{D} \end{bmatrix}' \begin{bmatrix} \underline{y} \\ \dots \\ \underline{0} \end{bmatrix}$$

This may not be the “best” solution because the introduction of $\underline{0}$ is arbitrary, although it is the “classical” ANOVA method.

The ideal method of reparameterization involves careful selection of the augmenting matrix. This allows us to test other parameters simultaneously as a component of the design.

$$\bar{y} = \mathbf{A} \xi + \underline{e} \rightarrow \text{with dimensions: } (n \times 1) = (n \times m)(m \times 1) + (n \times 1), \text{ where } n = \# \text{ of cells in design}$$

Let \mathbf{A} ($n \times m$) be of rank l , where $l \leq m$.

Let \mathbf{L} be of rank l and linearly dependent on rows of \mathbf{A} .

$$\text{Rank} \begin{bmatrix} \mathbf{A} \\ \dots \\ \mathbf{L} \end{bmatrix} = \text{Rank} (\mathbf{A}) = \text{Rank} (\mathbf{L}) = l$$

The key to the whole process is choosing \mathbf{L} .

The best reparameterization for solving equations involving a design matrix includes a set of a priori contrasts.

Consider a one-way design with 4-levels:

$$\bar{y} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{bmatrix} + \underline{e}$$

Examples of many possible \mathbf{L} s includes the following:

$$\text{Simple Contrasts: } \mathbf{L} = \begin{bmatrix} 1 & 1/4 & 1/4 & 1/4 & 1/4 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} \mu + \frac{\alpha_1 + \alpha_2 + \alpha_3 + \alpha_4}{4} \\ \alpha_1 - \alpha_4 \\ \alpha_2 - \alpha_4 \\ \alpha_3 - \alpha_4 \end{bmatrix}$$

Helmert Contrasts

$$L = \begin{bmatrix} 1 & 1/4 & 1/4 & 1/4 & 1/4 \\ 0 & 1 & -1/3 & -1/3 & -1/3 \\ 0 & 0 & 1 & -1/2 & -1/2 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} \dots \\ \alpha_1 - \frac{\alpha_2 + \alpha_3 + \alpha_4}{3} \\ \alpha_2 - \frac{\alpha_3 + \alpha_4}{2} \\ \alpha_3 - \alpha_4 \end{bmatrix}$$

Helmert contrasts are also orthogonal contrasts.

You can also create contrasts to assess your own specific research comparisons or a priori comparisons.